



# Getting Started with EPICS Applications / Special Topics

Introduction to synApps (v5.1)

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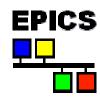


- A collection of EPICS applications for synchrotron-beamline users http://www.aps.anl.gov/aod/bcda/synApps
- EPICS modules and build/configuration tools:
  - Modules: autosave, calc, camac, ccd, dac128V, dxp, ip, ip330, ipUnidig, love, mca, motor, optics, quadEM, sscan, std, vme, xxx
  - Build/config: config and utils directories
- Related clients, libraries, and visualization tools:
  - IDL: scanSee, mca display, ezcaIDL, ezcaScan, ez\_fit, HDF translator/browser, Ascii-format plotter, image processors, etc.
  - CA-Server based CCD control
  - some python support





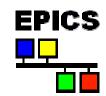
# synApps modules



- Modules contain the following kinds of support:
  - Compiled code; libraries
    - E.g., record and device support
    - State-Notation-Language programs
  - EPICS databases and autosave-request files
    - A database is a program written in a high-level language.
    - One or more copies of a database can be run, each with its own private variables (PV's).
    - The database designer recommends PV's to be autosaved by naming them in a .req file; you can override with a private copy of the file.
  - MEDM-display files
    - The default user interface
  - Documentation







# Other EPICS modules used by synApps

- asyn 4.1
- ipac 2.8
- seq 2.0.8 (9?)
- genSub 1.6
- vxStats 1.7.2c
- allenBradley 2.1





# autosave module



- Records latest values of selected EPICS PVs; restores those values when the ioc restarts.
  - not an archiver; only the latest value is saved
  - not the same as saveData, which writes scan data
  - When a list list of PV's is saved, the entire list is written, even if only one PV has changed.
- Can save/restore any scalar or array-valued PV (synApps 5.1)
  - Array-valued PV must be hosted by the ioc that does the restore operation. (Typically, all ioc's save/restore their own PV's.)
  - DBF\_MENU, DBF\_ENUM PV's are handled by number.
- Save operation uses channel access for scalars.
- Restore operation uses static database access for scalars.
- Arrays are saved and restored with database access.









# Three restore options for save files:

- 1) before record/device initialization
  - Motor positions must be restored at this time.
  - Arrays cannot be restored at this time. \*
  - PV's that are DBF\_NOACCESS before record init (e.g., genSub variable-type fields) cannot be restored at this time. \*
- 2) after record/device initialization
  - to override record-initialization values
  - Link fields cannot be restored at this time. \*
- 3) both before and after record initialization
  - The 'auto settings.sav' file is restored at both times.
  - It's not an error to attempt to restore a PV at the wrong time.
  - If you restore a motor position at this time, you override the value read from hardware, without writing to hardware.

<sup>\*</sup> Not illegal, just doesn't work









- PV lists can use include files (e.g., <database\_name>.req), include path.
  - Database developer can supply default include file with database.
  - User can override with custom include file.
- Save triggers:
  - on change of any PV in the list
  - periodically
  - on change of a trigger PV
  - manual
- User can reload save sets.
- Autosave can recover from file-server reboot (synApps 4.6+).
  - Currently, only on vxWorks
- User can choose to save redundant files (synApps 4.6+).
- Autosave reports status via EPICS PV's (synApps 5.1+).









# Sample request file

```
pv names

xxx:my_PV.VAL

xxx:my_array_PV.VAL

file motor_settings.req P=$(P),M=m1

...

<END><1f>
Name of include file
```

# Sample save file

```
# save/restore V4.4 Automatically generated...
xxx:my_PV.VAL 1.0
xxx:my_array_PV.VAL @array@ { "0" "0.1" ... "10.2" }
xxx:m1.DIR 0
xxx:m1.DHLM 100
xxx:m1.DLLM -100
...
```





# calc module



 Support for evaluation of string or numeric expressions entered at run time (or at database-configure time)

#### Records

- **sCalcout** like calcout, but also supports string expressions; user can specify wait-for-completion.
- **swait** like calcout, but uses recDynLink (no "PP MS" link attributes)
- transform like 16 calcout records that share a PV data pool

#### Other code

- string-calc engine
- sCalcout soft device support (with wait-for-completion option)
- interpolation routines for genSub record
- (yet another) averaging routine for sub record

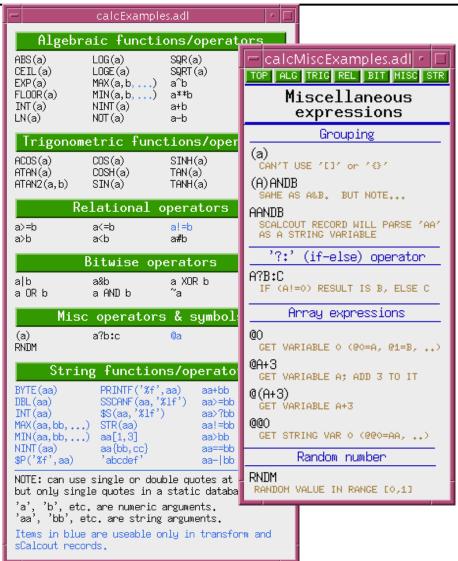




# ...calc module



- Databases, medm displays for run-time programming
  - userCalc
  - userStringCalc
  - userTransform
  - userAve
  - arrayTest
  - interpolation
- Examples of ALL calc expressions (normal and stringCalc) can be found in synApps MEDM help displays







# camac module



- Communication with CAMAC crate/modules
- Records
  - camac generic BCNAF/data for run-time camac control
- Devices supported
  - VME bus adapter
  - CAMAC crate controller
  - E500 motor controller
  - RTC-018 real-time clock
  - QS-450 quad scaler
  - DXP spectroscopy system (now in dxp module)





# ccd module



- Support for area detectors (CCD's and image plates)
- Supported devices
  - MAR 165 CCD
  - MAR 345 image-plate reader
  - Roper (all WinView-supported CCD's, including former Princeton and most former Photometrics devices)
  - Bruker SMART CCD
- Can control, at minimum
  - exposure time
  - file name
  - data-acquisition start
  - wait for acquisition to complete
  - much more for most devices
- See lecture "Detectors and Feedback."





# config directory



# Configures and builds all modules in or used by synApps

### MASTER\_RELEASE

 specifies version number and file path to EPICS base, and to every module in or used by synApps

### makeReleaseConsistent.pl

- Edits <module>/configure/RELEASE for every module in or used by synApps, to agree with MASTER\_RELEASE
- "gnumake release" causes this to run.

#### Makefile

 "gnumake <whatever>", in config directory, does <whatever> for all modules.





# dac128V module



- device support, database, and MEDM displays for dac128V IndustryPack module
  - 8-channel, 12-bit DAC
  - Support exists to run a DAC channel manually, or according to an algorithm written at run time, or as a *scan* positioner, or as part of a PID feedback loop.
- See lecture "Detectors and Feedback."









# TOP-level synApps documentation

- What synApps is
- How to build it
- How to make a user application from the 'xxx' sample module
- How to fit the user application to a particular set of hardware

# This presentation





# dxp module



- record, device support, databases, and MEDM displays for XIA
   DXP and Saturn spectroscopy systems
- dxp record for setting DXP parameters
- device support for the mca record
- See lecture "Detectors and Feedback."





# ip module



- device support, SNL code, databases, and MEDM displays for many message-based devices
  - originally, for devices supported via IndustryPack hardware
  - Note some of this support will inevitably be out of date -- pending access to hardware for testing.
- deviceCmdReply (was serial\_Ol\_block, GPIB\_Ol\_block)
  - Used to write support at run time for one command/reply message
  - sCalcout to format output string
  - asyn record to write/read device
  - sCalcout record to parse reply
- devXxStrParm device support
  - probably will be replaced by streams/asyn





# ip330 module



- device support, databases, and MEDM displays for the IP330 ADC IndustryPack module
- 16/32 channel, 16-bit ADC
  - ip330Scan for periodic, averaged reads of ADC channels
  - ip330Sweep, with the MCA record, for using ip330 as a waveformdigitizer
  - ip330PID for using the ip330 in a fast-feedback loop
- See lecture "Detectors and Feedback."





# ipUnidig module



- device support, databases, and MEDM displays for the IPUnidig digital I/O IndustryPack module
- IP-UD-I 24-channel input/output/interrupt module
- DIO316I 48-bit digital I/O module
- See lecture "Detectors and Feedback."





# love module



- Support for Love controllers
  - orphaned, currently under re-development for EPICS 3.14



# mca module



- Support for multichannel analyzers, multichannel scalers, and other array-valued detectors
- mca record
- device support
  - Canberra 556 AIM module (MCA and ICB controller)
  - DSA-2000 Ethernet MCA
  - various Canberra-ICB modules for spectroscopy
  - SIS 3801 (Struck STR7201) MCS
  - (DXP support in dxp module)
  - (IP330 support in ip330 module)
  - (quadEM support in quadEM module)
- See lecture "Detectors and Feedback."





# motor module



- Motor record and device support
  - stepper and servo motors
  - soft-motor support
    - Put motor "face" on, e.g., a DAC channel
    - Drive a hard motor through a nonlinear transform
  - user/dial/raw coordinates
  - backlash-takeout algorithm
  - pre/post move commands
  - many more features
- See lecture "Motors."





# optics module



#### Slits and mirrors

- Four virtual positioners; two real motors
- Automatic sync to motor positions
- Completion reporting

#### Monochromators

- Nondispersive double-crystal
  - Geometries: (Y1, Z2), (Y2, Z2)
  - Crystal species: Si, Ge, Diamond, Si (77K)
  - Miller indices, allowed reflections
  - Operational modes:
    - Use/Set
    - Manual/Auto
  - Managing the vertical beam offset
  - Automatic sync to motor positions





# ...optics module



#### ...Monochromators

- Spherical grating
  - Geometrical variables:
    - 1) Grating line density; radius
    - 2) Tangent-arm length
    - 3) Diffraction order
    - 4) Input/output slit distances
  - Operational modes:
    - Use/Set
    - Manual/Auto
  - Grating-stripe list
  - Manual sync to motor positions





# ...optics module



#### ...Monochromators

- Dispersive double-crystal
  - Geometries: nested, symmetric
  - Crystal species: Si, Ge, Diamond, Si (77K)
  - Miller indices, allowed reflections
  - Operational modes:
    - Use/Set
    - Manual/Auto
    - Theta1 / Theta1&2 / Rock Theta2
  - Accommodate incident-beam angle shift ("world offset")
  - Automatic sync to motor positions





# ...optics module



### Optical table

- **Table** record supports a six-degree-of-freedom optical table.
- User/client can write either to  $(x, y, z, \theta_X, \theta_Y, \theta_Z)$ , or to underlying motor records.
- Table rotates about user-specified point.
- Table database includes a list of rotation points, selected by menu.
- Can recover table position from motor positions
- Partial support for fewer than six degrees of freedom



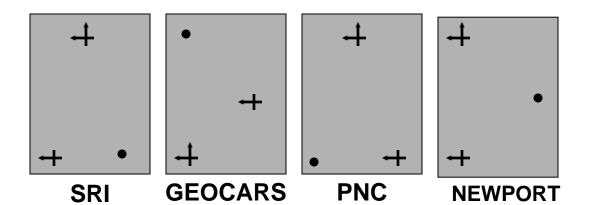






### Optical table

- Geometries
  - SRI
  - GeoCARS
  - Newport
  - PNC



### - Calibration/sync

- Use/Set changes to [X, Y, ..]. move table / change calibration
- Zero redefine current [X, Y, ...] as zero
- Sync update [X, Y, ...] from motors, honoring calibration
- Init clear calibration and sync to motors
- Table record sets motor speeds so that motors start/stop together.





# quadEM module



- Support for APS Detector Group's (Steve Ross) four-input electrometer.
- See lecture "Detectors and Feedback."



# sscan module



- Support for user-programmable data-acquisition
  - sscan and busy records
  - saveData
  - recDynLink

#### A one-dimensional scan:

- Do NPTS times:

- Set conditions e.g., move motors; wait for completion

- Trigger detectors e.g., start scaler; wait for completion

Acquire data read detector signals; store in arrays

Write data to NFS file

#### Multidimensional scan:

- Same as a 1-D, but detector trigger executes inner-loop scan.
- saveData monitors a set of sscan records, determines scan dimension when scan starts, and writes data as it is acquired.





# ...sscan module



#### scan features:

- Three 1-D scan types: constant-step-size, table-driven, fly
- Unlimited number of data points, scan dimensions
- 0-4 positioners, 0-4 detector triggers, 0-70 detector signals
- Acquisition from scalar and 1-D-array-valued PV's
- Detector/client wait, data-storage wait
- Pause/resume, abort
- Double buffered: can write 1-D acquired data during next 1-D scan
- saveData writes self-describing XDR-format (".mda") files to NFS-mounted disk (vxWorks only, at present).
- A positioner can have private scan parameters (scanparm record).
- After-scan actions include move to peak, valley, and edge.
- scanparm record + after-scan action = automated 1-D alignment, so you can easily implement an "Align" button.





# ...sscan module



#### The sscan record

- performs 1-D scan
- before-scan link optional completion callback
- positioner: any writable, numeric, scalar PV (menus, enums are ok)
- detector trigger: any writable, numeric, scalar PV
- detector signal: any readable, numeric, scalar or 1D array PV
- array detectors: exactly <scanRecord>.NPTS elements are acquired
- array trigger: callback indicates array data are ready to read
- after-scan link optional completion callback
- pause/resume
- abort (<scanRecord>.EXSC -> 0) wait for callbacks, cleanup
- kill (two aborts in a row) abandon callbacks
- handshake with multiple display / data-acquisition clients
- handshake with data-storage client







# Other data-acquisition-related software

# Data-visualization tools for use with synApps

- Run-time look at scan data
- Offline tools for data-file manipulation
- Supports 1-3 dimensional data
- Distributed independently of ioc software
- See lecture "Data Visualization."

# CCD data-acquisition tools

- 1) CCD module (see lecture "Detectors and Feedback")
- 2) Portable CA Server based CCD support, and related software
  - http://www.aps.anl.gov/aod/bcda/dataAcq/index.php
- Both of these solutions allow an EPICS CA client to drive data acquisition.
- Both support ca\_put\_callback(), as required by the sscan record.





# std module



#### Epid record

- Extended PID record – see "**Detectors and feedback**" lecture

#### Scaler record

- Controls a set of counters with a common clock, gate, and trigger

#### String-sequence record

- Like the seq record in base, but works for strings and numbers
- Can choose to wait for completion after each step in sequence

#### Soft-motor database (Jonathan Lang)

- Run-time programmable soft-motor/transform/hard-motor database
- Quick solution for driving a motor through a nonlinear transform

#### Timestamp record [SLAC]

needed by SNS' vxStats; currently not available in a module

#### 4-step database

- Up to four steps of (set condition; read data) with an end calculation
- Originally developed for dichroism experiments





# utils directory



### changePrefix

 Global search and replace of EPICS PV prefix within a copy of the xxx module

# copyAdI

 Find all MEDM-display files buried in a file tree; copy to specified directory.



# vme module



#### VME record

- Provides run-time access to VME bus
- Great for testing hardware
- Run-time programmed control of an unsupported VME board

### Device support for VME hardware

- Joerger scaler
- APS bunch-clock generator
- APS machine-status interface
- Heidenhain encoder interpolator
- Generic A32 VME interface
- HP Laser interferometer
- VMI4116 16-bit DAC
- Acromag 9440 16-bit digital input





# xxx module



### Prototype user directory

- Builds everything in synApps into a load module
- Contains command files to load/configure everything in synApps
- Contains sample top-level MEDM-display file
- Contains sample script to set environment variables and start up the sample user interface
- Contains table of recommended address/interrupt configuration for selected VME and IndustryPack hardware

# Two ways to use this module

- 1) Make copies; run changePrefix; build; customize; run a beamline
  - this is the recommended use
  - detailed instructions in support/documentation
- 2) Reference/grab bag







# For developers: features of synApps

### extended-processing records

 records that are neither synchronous nor asynchronous, as these terms are described in the EPICS Application Developer's Guide

### completion reporting

- All databases behave correctly when written to by ca\_put\_callback().

### recDynLink links

- Similar to standard EPICS links, but no "PP NMS" attributes

#### GUI standards

- Default colors for menus, PV values, links, etc.

#### coordinated motions

- Many of the databases in synApps (especially in 'optics') involve coordinated motion of several motors.

# initialization of complex databases

- Some common EPICS initialization problems are handled in various synApps databases.





# **Coordinated motions**



- Simple cases: database (transform records)
  - Slits, mirrors, spherical-grating monochromator
- More complicated cases: SNL code
  - Multiple-crystal monochromators
- Very complicated cases: custom record
  - Optical table, scan
- Criteria a useful coordination should meet:
  - Report completion to ca\_put\_callback()
  - Share control of base positioners with CA clients
  - Recover state from the states of base positioners





# **Completion reporting**



- Simple prescription for databases contained within a single ioc:
  - Use only PP links and forward links in execution chain.
- Database operations spanning more than one ioc:
  - Use records with put\_callback links to span iocs:
    - calcout with asynchronous device support
    - sscan, swait
    - sseq or sCalcout (with .WAIT\* = "Wait")
- Cases in which a CA client performs part of the operation:
  - 1) Database sets a **busy** record via PP or put\_callback link.
  - 2) CA client clears the **busy** record when operation is done.
- Cases in which part of the operation is driven by a CP link:
  - Not different from above; a CP link is a CA client









# Initialization of complex databases

- Initial values: .VAL vs. .DOL
  - Most records allow .VAL field to be set in the database.
  - Note that .DOL cannot be used for constant strings.

#### Save-restore and interaction with record/device initialization

- 1) save-restore pass 0
- 2) record/device initialization → device support can use pass-0 value
- 3) save-restore pass 1  $\rightarrow$  pass-1 overrides record/device-init value

# .PINI (Process at INIt) uses and limitations

- This is the normal mechanism for database initialization.
- What if you need a value from some other .PINI-initialized record, and that record hasn't processed yet?
- Note .PHAS is not considered in .PINI processing.







# ...Initialization of complex databases

### Contending with link alarms

- If you have an input link to a record with .UDF=1, you get a link alarm.
- .UDF=1 until a record processes. (In 3.14.1+, database can specify .UDF)
- > The transform record can abort execution on a link alarm (or not).

# Initialization problems with CP links

- You have a CP link to a field that is a calculation result.
- If the calc result is the same as the field's initial value, you'll have the right value, but you won't *know* that you have the right value, and you won't know for how long to wait to be sure.
- > The transform record *always* posts its initial calculation result.

# Programmatically initializing link fields

- Link field must be written with a CA link (because lock-set recalc).
- .PINI processing occurs *before* CA is running (EPICS 3.13.5+).
- Can't use .PINI; Drive init from a scan task; set init record to "Passive" when init is done.



